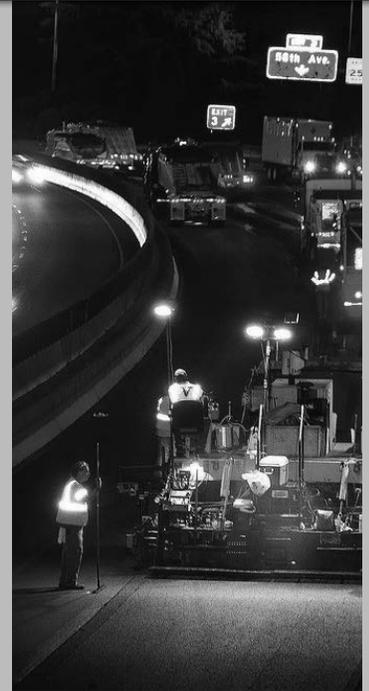




Mechanistic-Empirical Pavement Design Guide

~ A Manual of Practice ~



2020 • Third Edition

Preface

This document or manual of practice describes a pavement design methodology that is based on engineering mechanics and has been validated with extensive road test performance data. This methodology is termed mechanistic-empirical (ME) pavement design, and it represents a major change from the pavement design methods in practice today.

Interested agencies have already begun implementation activities through staff training, collection of input data (materials library, traffic library, etc.), acquiring of test equipment, and preparation of field sections for local calibration. This manual, referred to as the Mechanistic-Empirical Pavement Design Guide (MEPDG), presents the information necessary for pavement design engineers to start using the ME-based design and analysis method. The software supporting this method is called Pavement ME Design[®] and is commercially available through AASHTOWare. The software is referred to in this document as PMED.

Multiple enhancements have been made to the AASHTOWare PMED based on completed research projects sponsored by the National Cooperative Highway Research Program (NCHRP) and the Federal Highway Administration (FHWA). In addition, revisions to the software were based on evaluations performed by State Highway Agencies and others in the Community of Practice. The third edition of the MEPDG Manual of Practice was prepared so the manual was consistent with the enhanced features and models included in the software through 2018.

The following table (Table P-1) summarizes the key differences noted between the format and calibration factors used in the MEPDG version 1.1 software, the AASHTOWare Pavement ME Design software version 2.3.1, and version 2.5.3 software.

Table P-1. Summary of Key Differences in Software Format and Calibration Factors

Format, Transfer Functions, and Calibration Coefficients		MEPDG version 1.1	AASHTOWare Pavement ME Design version 2.3.1	AASHTOWare Pavement ME Design version 2.5.3
Output Format		Excel-based	PDF- and Excel-based	PDF- and Excel-based
Climatic Input Data and if Included in Output Summary		Data from Ground-Based Weather Stations; output summary not included	Data from NARR database for rigid and flexible pavements; output summary included	Data from NARR database for rigid pavements and MERRA2 database for flexible and semi-rigid pavements; output summary included
Axle Configuration Data in Output Summary		Not included	Included	Included
Special Axle Load Configuration		Included	Not included	Not included
Reflection Cracking Transfer Function		Empirical regression equation included	ME-based fracture mechanics model included	ME-based fracture mechanics model included
Coefficient of Thermal Expansion (CTE)		CTE for Basalt of 4.6	CTE for Basalt of 4.3	CTE for Basalt of 4.3
PCC Zero Stress Temperature		PCC Zero Stress Temperature (60°–120°F)	PCC Set Temperature (70°–212°F)	PCC Set Temperature (70°–212°F)
Heat Capacity of Asphalt Pavement		Default value of 0.23 BTU/lb-°F	Default value of 0.28 BTU/lb-°F	Default value of 0.28 BTU/lb-°F
Thermal Conductivity of Asphalt Pavement		Default value of 0.67 BTU/(ft)(hr)(F)	Default value of 1.25 BTU/(ft)(hr)(F)	Default value of 1.25 BTU/(ft)(hr)(F)
Surface Shortwave Absorptivity		Default value of 0.95	Default value of 0.85	Default value of 0.85
Global Model Coefficient for Unbound Materials and Soils in Flexible Pavement Subgrade Rutting Model	Aggregate Base	k_{s1} of 1.673	k_{s1} of 2.03	k_{s1} of 0.965
	Coarse-Grained Soil			k_{s1} of 0.965
	Sand Soil			k_{s1} of 0.635
	Fine-Grained Soil	k_{s1} of 1.35	k_{s1} of 1.35	k_{s1} of 0.675

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Table P-1. Summary of Key Differences in Software Format and Calibration Factors, *continued*

Format, Transfer Functions, and Calibration Coefficients		MEPDG version 1.1	AASHTOWare Pavement ME Design version 2.3.1	AASHTOWare Pavement ME Design version 2.5.3
Global Local Calibration or Field Adjustment Constant for Unbound Materials and Soils in Flexible Pavement Subgrade Rutting Model	Aggregate Base	1.0	1.0	1.0
	Coarse-Grained Soil			1.0
	Sand Soil			1.0
	Fine-Grained Soil			1.0
Global Laboratory-Derived Model Coefficients in the Fatigue Cracking Prediction Model in Flexible Pavement		k_{s1} of 0.007566	k_{s1} of 0.007566	k_{s1} of 3.75
		k_{s2} of -3.9492	k_{s2} of 3.9492	k_{s2} of 2.87
		k_{s3} of -1.281	k_{s3} of 1.281	k_{s3} of 1.46
Global Local Calibration or Field-Adjustment Constants for Fatigue Cracking Prediction Model in Flexible Pavement		β_1 of 1.0	β_1 of 1.0	AC thickness dependent; see Chapter 5
		β_2 of 1.0	β_2 of 1.0	β_2 of 1.38
		β_3 of 1.0	β_3 of 1.0	β_3 of 0.88
Global Bottom-Up Alligator Cracking Transfer Function Coefficients		C_1 of 1.0	C_1 of 1.0	1.31
		C_2 of 1.0	C_2 of 1.0	AC thickness dependent; see Chapter 5
Global Calibration or Field-Adjustment Coefficient in the Transverse Cracking Model for AC		k_t (Level 1) of 5.0	k_t (Level 1) of 1.5	k_s (Level 1) is Mean Annual Air Temperature (MAAT) dependent; see Chapter 5.
		k_t (Level 2) of 1.5	k_t (Level 2) of 0.5	k_s (Level 2) is MAAT dependent; see Chapter 5.
		k_t (Level 3) of 3.0	k_t (Level 3) of 1.5	k_s (Level 3) is MAAT dependent; see Chapter 5.
Global Laboratory Derived Model Coefficients in the Rut Depth Prediction Model		k_1 of -3.35412	k_1 of -3.35412	k_1 of -2.45
		k_{2r} of 0.4791	k_2 of 1.5606	k_2 of 3.01
		k_{3r} of 1.5606	k_3 of 0.4791	k_3 of 0.22

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Table P-1. Summary of Key Differences in Software Format and Calibration Factors, *continued*

Format, Transfer Functions, and Calibration Coefficients	MEPDG version 1.1	AASHTOWare Pavement ME Design version 2.3.1	AASHTOWare Pavement ME Design version 2.5.3
Global Local Calibration or Field Adjustment Coefficients in the Rut Depth Prediction Model	β_1 of 1.0	β_1 of 1.0	β_1 of 0.40
	β_2 of 1.0	β_2 of 1.0	β_2 of 0.52
	β_3 of 1.0	β_3 of 1.0	β_3 of 1.36
Calibration Coefficients in the Rigid Pavement Cracking Prediction Model	C_4 of 1.0	C_4 of 0.52	C_4 of 0.52
	C_5 of -1.98	C_5 of -2.17	C_5 of -2.17
Calibration Coefficients in the Rigid Pavement Faulting Prediction Model	C_1 of 1.29	C_1 of 1.0184	C_1 of 0.595
	C_2 of 1.1	C_2 of 0.91656	C_2 of 1.636
	C_3 of 0.001725	C_3 of 0.0021848	C_3 of 0.00217
	C_4 of 0.0008	C_4 of 0.0008837	C_4 of 0.00444
	C_6 of 0.4	C_6 of 0.47	C_6 of 0.47
	C_7 of 1.2	C_7 of 1.83312	C_7 of 7.3
Calibration Coefficient in the Rigid Pavement Punchout Prediction Model	A_{PO} of 195.789	C_3 of 107.73	C_3 of 107.73
	α_{PO} of 19.8947	C_4 of 2.476	C_4 of 2.475
	β_{PO} of -0.526316	C_5 of -0.785	C_5 of -0.785
Calibration Coefficients in the Short JPCP Overlay Longitudinal Cracking Prediction Model	Excluded	C_4 of 0.4	C_4 of 0.4
		C_5 of -2.21	C_5 of -2.21

Table of Contents

Committee on Materials and Pavement Technical Subcommittee 5d on Pavement Design ..	iii
Preface	v
List of Figures	xiii
List of Tables	xvii
1. Introduction	1
1.1 Purpose of Manual	1
1.2 Overview of the Design Procedure	1
2. Referenced Documents and Standards	11
2.1 Test Protocols and Standards	11
2.1.1 Laboratory Materials Characterization	11
2.1.2 In-Place Materials/Pavement Layer Characterization	13
2.2 Material Specifications	13
2.3 Recommended Practices and Terminology	13
2.4 Referenced Documents	14
3. Significance and Use of the MEPDG	17
3.1 MEPDG Performance Indicators	17
3.2 MEPDG General Design Approach	18
3.3 New Flexible Pavement and AC Overlay Design Strategies Applicable to the MEPDG	20
3.4 New Rigid Pavement, PCC Overlay, and Restoration of Rigid Pavement Design Strategies Applicable for Use with the MEPDG	23
3.5 Design Features and Factors Not Included within the MEPDG Process	27
4. Terminology and Definition of Terms	31
4.1 General Terms	31
4.2 Hierarchical Input Levels	33
4.3 Truck Traffic Terms	33
4.4 Smoothness	34
4.5 Distresses or Performance Indicators Terms—AC-Surfaced Pavements	35
4.6 Distress or Performance Indicators Terms—PCC-Surfaced Pavements	36
5. Performance Indicator Prediction Methodologies	39
5.1 Selecting the Input Levels	39
5.2 Calibration Factors	40
5.3 Distress Prediction Equations for Flexible Pavements and AC Overlays	40
5.3.1 Overview of Computational Methodology for Predicting Distress	40
5.3.2 Rut Depth	43
5.3.3 Load-Related Cracking	46

5.3.4	Non-Load Related Cracking—Transverse Cracking	51
5.3.5	Reflection Cracking in AC Overlays and AC Layers of Semi-Rigid Pavements	55
5.3.6	Smoothness.	61
5.4	Distress Prediction Equations for Rigid Pavements and PCC Overlays	63
5.4.1	Transverse Slab Cracking (Bottom-Up and Top-Down)—JPCP	63
5.4.2	Mean Transverse Joint Faulting—JPCP	66
5.4.3	CRCP Punchouts.	74
5.4.4	Longitudinal Slab Cracking—SJPCP on Flexible Pavements.	77
5.4.5	Smoothness—JPCP	80
5.4.6	Smoothness—CRCP	82
6.	General Project Information.	85
6.1	Design/Analysis Life.	85
6.2	Construction and Traffic Opening Dates.	85
7.	Selecting Design Criteria and Reliability Level	87
7.1	Recommended Design-Performance Criteria	87
7.2	Reliability	88
7.3	Design Reliability Concept for Smoothness (IRI)	90
8.	Determining Site Conditions and Factors.	93
8.1	Truck Traffic.	93
8.1.1	Roadway-Specific Inputs.	95
8.1.2	Inputs Extracted from WIM Data	96
8.1.3	Truck Traffic Inputs Not Included in the WIM Data	101
8.2	Climate	102
8.3	Foundation and Subgrade Soils.	103
8.3.1	Subsurface Investigations for Pavement Design.	103
8.3.2	Laboratory and Field Tests of Soils for Pavement Design	105
8.4	Existing Pavements	105
9.	Pavement Evaluation for Rehabilitation Design.	109
9.1	Overall Condition Assessment and Problem Definition Categories.	109
9.2	Data Collection to Define Condition Assessment	113
9.2.1	Initial Pavement Assessment	117
9.2.2	Prepare Field Evaluation Plan	118
9.2.3	Conduct Condition or Visual Survey	118
9.2.4	Ground Penetrating Radar Survey	122
9.2.5	Refine Field Testing Plan	122
9.2.6	Conduct Deflection Basin Tests.	122
9.2.7	Destructive Sampling and Testing—Recover Cores and Boring for the Existing Pavement	124
9.2.8	Laboratory Tests for Materials Characterization of Existing Pavements.	128

9.3	Analysis of Pavement Evaluation Data for Rehabilitation Design Considerations . . .	130
9.3.1	Visual Distress Survey to Define Structural Adequacy	131
9.3.2	Backcalculation of Layer Modulus Values	132
9.3.3	Loss of Support Detection	134
9.3.4	Joint or Crack Load Transfer Efficiency	134
9.3.5	Variability along a Project	137
10.	Determination of Material Properties for New Paving Materials	139
10.1	Material Inputs and the Hierarchical Input Concept	139
10.2	AC Mixtures, Including SMA, Asphalt Treated or Stabilized Base Layers, and Asphalt Permeable Treated Base Mixes	139
10.3	PCC Mixtures, Lean Concrete, and Cement Treated Base Layers	149
10.4	Chemically Stabilized Materials, Including Lean Concrete and Cement Treated Base Layers	149
10.5	Unbound Aggregate Base Materials and Engineered Embankments	156
11.	Pavement Design Strategies	161
11.1	New Flexible Pavement Design Strategies—Developing the Initial Trial Design . . .	161
11.1.1	Should the Subgrade Soil be Strengthened or Improved?	162
11.1.2	Is a Rigid Layer or Water Table Present?	162
11.1.3	Is a Compacted Embankment or Improved Subgrade Layer Present?	164
11.1.4	Should a Drainage Layer Be Included in the Design Strategy?	164
11.1.5	Use of a Stabilized Subgrade for Structural Design or a Construction Platform?	165
11.1.6	Should an Aggregate Base/Subbase Layer Be Placed?	165
11.1.7	AC Layers—What Type and How Many?	166
11.1.8	What Initial IRI Value Should Be Used?	166
11.2	New Rigid Pavement Design Strategies—Developing the Initial Trial Design	168
11.2.1	Structure—Trial Layer Type, Thickness, and Design Features	168
11.2.2	JPCP Design	169
11.2.3	CRCP Design	171
11.2.4	Initial Surface Smoothness	173
11.2.5	Narrow or Widened Slabs	174
12.	Rehabilitation Design Strategies	175
12.1	General Overview of Rehabilitation Design	175
12.2	Rehabilitation Design with AC Overlays	177
12.2.1	Overview	177
12.2.2	AC Overlay Analyses and Trial Rehabilitation Design	177
12.2.3	Determine Condition of Existing Pavement	178
12.2.4	Decide on Pre-Overlay Treatment	179
12.2.5	Determination of Damaged Modulus of Bound Layers and Reduced Interface Friction	183

12.2.6	AC Overlay Options of Existing Pavements	184
12.2.7	AC Overlays of Existing AC Pavements, Including Semi-Rigid Pavements . .	185
12.2.8	AC Overlays of Existing Intact PCC Pavements, Including Composite Pavements (One or More AC overlays of Existing JPCP and CRCP)	186
12.2.9	AC Overlay of Fractured PCC Pavements	190
12.3	Rehabilitation Design with PCC Overlays	197
12.3.1	Overview	197
12.3.2	Analysis Parameters Unique to Rehabilitation	199
12.3.3	Estimate of Past Damage (for JPCP Subjected to CPR)	200
12.3.4	JPCP Rehabilitation Design	203
12.3.5	CRCP Rehabilitation Design	212
12.3.6	Additional Considerations for Rehabilitation with PCC	215
13.	Interpretation and Analysis of the Trial Design	217
13.1	Summary of Inputs for the Trial Design	217
13.2	Reliability of Trial Design	217
13.3	Supplemental Information (Layer Modulus, Truck Applications, and Other Factors) . .	219
13.4	Predicted Performance Values	220
13.5	Judging the Acceptability of the Trial Design	222
	Abbreviations and Terms	227
	Index	235

List of Figures

Figure 1-1.	Conceptual Flow Chart of the Three-Stage Design/Analysis Process for AASHTOWare PMED	3
Figure 1-2.	Typical Differences between Empirical Design Procedures and an Integrated ME Design System, in Terms of AC Mixture Characterization	4
Figure 1-3.	Typical Differences between Empirical Design Procedures and an Integrated ME Design System, in Terms of PCC-Mixture Characterization.	5
Figure 1-4.	Flow Chart of the Steps That Are More Policy Decision Related and Needed to Complete an Analysis of a Trial Design Strategy	7
Figure 1-5.	Flow Chart of the Steps Needed to Complete an Analysis of a Trial Design Strategy.	8
Figure 3-1.	New (Including Lane Reconstruction) Flexible Pavement Design Strategies That Can Be Simulated with the AASHTOWare PMED	21
Figure 3-2.	AC Overlay Design Strategies of Flexible, Semi-Rigid, and Rigid Pavements That Can Be Simulated with the AASHTOWare PMED	21
Figure 3-3.	New (Including Lane Reconstruction) Rigid Pavement Design Strategies That Can Be Simulated with the AASHTOWare PMED	25
Figure 3-4.	PCC Overlay Design Strategies of Flexible, Semi-Rigid, and Rigid Pavements That Can Be Simulated with the AASHTOWare PMED	26
Figure 5-1.	Graphical Illustration of the Five Temperature Quintiles Used in the MEPDG to Determine AC Mixture Properties for Load Related Distresses.	42
Figure 5-2.	Comparison of Measured and Predicted Total Rutting Resulting from Global Calibration Process.	46
Figure 5-3.	Comparison of Cumulative Fatigue Damage and Alligator Cracking Resulting from Global Calibration Process.	49
Figure 5-4.	Comparison of Measured and Predicted Lengths of Longitudinal Cracking (Top-Down Cracking) Resulting from Global Calibration Process	50
Figure 5-5.	Comparison of Measured and Predicted Transverse Cracking Resulting from Global Calibration Process.	53
Figure 5-6.	Response Mechanisms Used in Reflection Cracking Prediction Methodology	55
Figure 5-7.	Mechanisms of Thermally Induced Reflective Cracks of AC Overlays	55
Figure 5-8.	Mechanisms of Traffic Induced Reflective Cracks of AC Overlays	56
Figure 5-9.	Comparison of Measured and Predicted IRI Values Resulting from Global Calibration Process of Flexible Pavements and AC Overlays of Flexible Pavements	62

Figure 5-10.	Comparison of Measured and Predicted IRI Values Resulting from Global Calibration Process of AC Overlays of PCC Pavements and Semi-Rigid Pavements	62
Figure 5-11.	Comparison of Measured and Predicted Percentage JPCP Slabs Cracked Resulting from Global Calibration Process.	65
Figure 5-12.	Comparison of Measured and Predicted Transverse Cracking of Unbounded JPCP Overlays Resulting from Global Calibration Process	65
Figure 5-13.	Comparison of Measured and Predicted Transverse Cracking for Restored JPCP Resulting from Global Calibration Process.	66
Figure 5-14.	Comparison of Measured and Predicted Transverse Joint Faulting for New JPCP Resulting from Global Calibration Process.	72
Figure 5-15.	Comparison of Measured and Predicted Transverse Joint Faulting for Unbound JPCP Overlays Resulting from Global Calibration Process	73
Figure 5-16.	Comparison of Measured and Predicted Transverse Joint Faulting for Restored (Diamond Grinding) JPCP Resulting from Global Calibration Process	73
Figure 5-17.	Comparison of Measured and Predicted Punchouts for New CRCP Resulting from Global Calibration Process.	77
Figure 5-18.	Illustration of Proper Location of Longitudinal Joints to Avoid Overlap with Truck Wheel Paths (to Avoid Corner Cracking) and the Resulting Critical Bending Stresses at Bottom of Slab That Are Considered to Limit Longitudinal Fatigue Cracking	78
Figure 5-19.	Measured Longitudinal Fatigue Cracking (LCRK) versus PCC Fatigue Damage (DIF) at Bottom of PCC Slab	79
Figure 5-20.	Comparison of Measured and Predicted Percentage SJPCP Overlay Slabs Longitudinally Cracked Resulting from Global Calibration Process.	80
Figure 5-21.	Comparison of Measured and Predicted IRI Values for New JPCP Resulting from Global Calibration Process.	82
Figure 5-22.	Comparison of Measured and Predicted IRI Values for New CRCP Resulting from Global Calibration Process.	83
Figure 7-1.	Design Reliability Concept for Smoothness (IRI).	89
Figure 8-1.	Comparison of the Five NALS Defaults for Vehicle Class 9 Tandem Axles—Entire Range of Axle Loads.	98
Figure 8-2.	Comparison of the Five NALS Defaults for Vehicle Class 9 Tandem Axles—Axle Loads between 32,000–50,000 lb.	98
Figure 9-1.	Steps and Activities for Assessing Condition of Existing Pavements for Rehabilitation Design (Refer to Table 9-2).	114

Figure 9-2.	Location of the Loading Plate and Sensor Relative to the Joint or Transverse Crack for Measuring LTE	124
Figure 9-3.	Schematic of the LTE for Two Cases.....	135
Figure 11-1.	Flow Chart to Select Some Options and Minimize the Effect of Problem Soils on Pavement Performance	163
Figure 11-2.	Limiting Modulus Criteria of Unbound Aggregate Base and Subbase Layers....	167
Figure 12-1.	Steps for Determining a Preferred Rehabilitation Strategy	176
Figure 12-2.	Flow Chart of Rehabilitation Design Options Using AC Overlays.....	178
Figure 12-3.	Site Features Conducive to the Selection of the Rubblization Process for Rehabilitating PCC Pavements.....	193
Figure 12-4.	Recommendations for a Detailed Investigation of the PCC Pavement to Estimate Remaining Life and Identify Site Features and Conditions Conducive to the Rubblization Process.....	194
Figure 12-5.	Evaluate Surface Condition and Distress Severities on Selection of Rubblization Option	195
Figure 12-6.	Foundation Support Conditions Related to the Selection of the Rubblization Process	196
Figure 12-7.	Overall Design Process for Major PCC Rehabilitation Strategies of All Pavement Types	199

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List of Tables

Table P-1.	Summary of Key Differences in Software Format and Calibration Factors	vi
Table 5-1.	Typical Input Levels Used in the Global Calibration of the AASHTOWare PMED Models and Transfer Functions	41
Table 5-2.	Global Calibration Coefficients for the Reflection Cracking Transfer Functions for Transverse Cracks	59
Table 5-3.	Global Calibration Coefficients for the Reflection Cracking Transfer Functions for Fatigue Cracks	60
Table 5-4.	Standard Deviation Equations for the Transverse Cracks	60
Table 5-5.	Standard Deviation Equations for the Fatigue Cracks	60
Table 5-6.	Assumed Effective Base LTE for Different Base Types	69
Table 7-1.	Design Criteria or Threshold Values Recommended for Use in Judging the Acceptability of a Trial Design	88
Table 7-2.	Suggested Minimum Levels of Reliability for Different Functional Classifications of the Roadway	91
Table 8-1.	Minimum Sample Size (Number of Days per Year) to Estimate the Normalized Axle Load Distribution—WIM Data	94
Table 8-2.	Minimum Sample Size (Number of Days per Season) to Estimate the Normalized Truck Traffic Distribution—Automated Vehicle Classifier (AVC) Data	94
Table 8-3.	Normalized Axle Load Distribution Included with the AASHTOWare PMED Software	97
Table 8-4.	TTC Group Description and Corresponding Truck Class Distribution Default Values Included in the AASHTOWare PMED Software	100
Table 8-5.	Definitions and Descriptions for the TTC Groups	101
Table 8-6.	Summary of Soil Characteristics as a Pavement Material	106
Table 9-1.	Checklist of Factors for Overall Pavement Condition Assessment and Problem Definition	111
Table 9-2.	Hierarchical Input Levels for a Pavement Evaluation Program to Determine Inputs for Existing Pavement Layers for Rehabilitation Design	115
Table 9-3.	Field Data Collection and Evaluation Plan	119
Table 9-4.	Guidelines for Obtaining Non-Materials Input Data for Pavement Rehabilitation	120

Table 9-5.	Use of Deflection Basin Test Results for Selecting Rehabilitation Strategies and in Estimating Inputs for Rehabilitation Design	123
Table 9-6.	Summary of Destructive Tests, Procedures, and Inputs for the MEPDG	125
Table 9-7.	Models/Relationships Used for Determining Level 2 E or M_r	126
Table 9-8.	Models Relating Material Index and Strength Properties to M_r	127
Table 9-9.	Distress Types and Severity Levels Recommended for Assessing Rigid Pavement Structural Adequacy	131
Table 9-10.	Distress Types and Levels Recommended for Assessing Current Flexible Pavement Structural Adequacy	132
Table 9-11.	LTE Values for Rehabilitation Design	136
Table 9-12.	LTE Default Values for Input Level 3 Tied to Crack Severity Level	136
Table 10-1.	Major Material Types for the MEPDG	140
Table 10-2.	Asphalt Materials and the Test Protocols for Measuring the Material Property Inputs for New and Existing AC Layers, Input Level 1	141
Table 10-3.	Recommended Input Parameters and Values; Limited or No Testing Capabilities for AC (Input Levels 2 and/or 3)	146
Table 10-4.	PCC Material Input Level 1 Parameters and Test Protocols for New and Existing PCC	150
Table 10-5.	Recommended Input Parameters and Values; Limited or No Test Capabilities for PCC Materials (Input Levels 2 or 3)	151
Table 10-6.	Chemically Stabilized Materials Input Level 1 Requirements and Test Protocols for New and Existing Chemically Stabilized Materials	154
Table 10-7.	Recommended Input Levels 2 and 3 Parameters and Values for Chemically Stabilized Material Properties	155
Table 10-8.	C-Values to Convert the Calculated Layer Modulus Values to an Equivalent Resilient Modulus Measured in the Laboratory	156
Table 10-9.	Unbound Aggregate Base, Subbase, Embankment, and Subgrade Soil Input Level 1 Material Requirements and Test Protocols for New and Existing Materials	157
Table 10-10.	Recommended Levels 2 and 3 Input Parameters and Values for Unbound Aggregate Base, Subbase, Embankment, and Subgrade Soil Material Properties	158
Table 11-1.	General IRI Recommendations	167
Table 11-2.	Friction Coefficient Values for CRCP Design	172
Table 12-1.	Definitions of Surface Condition for Input Level 3 Pavement Condition Ratings and Suggested Rehabilitation Options	180

Table 12-2.	Candidate Repair and Preventive Treatments for Flexible, Rigid, and Composite Pavements	181
Table 12-3.	Summary of Major Rehabilitation Strategies and Treatments Prior to Overlay Placement for Existing AC and AC/PCC Pavements	182
Table 12-4.	Data Required for Characterizing Existing PCC Slab Static Elastic Modulus for AC Overlay Design	189
Table 12-5.	Recommendations for Performance Criteria for AC Overlays of JPCP and CRCP	190
Table 12-6.	Recommendations for Modifying Trial Design to Reduce Distress/Smoothness for AC Overlays of JPCP and CRCP	191
Table 12-7.	PCC Rehabilitation Options—Strategies to Correct Surface and Structural Deficiencies of All Types of Existing Pavement	198
Table 12-8.	Summary of Key Aspects of Joint Design and Interlayer Friction for JPCP Overlays	201
Table 12-9.	Data Required for Characterizing the Existing PCC Slab	202
Table 12-10.	Description of Existing Pavement Condition	202
Table 12-11.	Summary of Factors that Influence Rehabilitated JPCP Distress	205
Table 12-12.	Guidance on How to Select the Appropriate Design Features for Rehabilitated JPCP Design	208
Table 12-13.	Recommendations for Modifying Trial Design to Reduce Distress/Smoothness for JPCP Rehabilitation Design	210
Table 12-14.	Summary of Factors that Influence Rehabilitated CRCP Distress and Smoothness	213
Table 12-15.	Guidance on How to Select the Appropriate Design Features for Rehabilitated CRCP Design	214
Table 13-1.	Reliability Summary for Flexible Pavement Trial Design Example	218
Table 13-2.	Reliability Summary for JPCP Trial Design Example	218
Table 13-3.	Guidance for Modifying AC Trial Designs to Satisfy Performance Criteria	223
Table 13-4.	Guidance for Modifying JPCP Trial Designs to Satisfy Performance Criteria	225
Table 13-5.	Guidance for Modifying CRCP Trial Designs to Satisfy Performance Criteria	226



Introduction

The overall objective of the Mechanistic-Empirical Pavement Design Guide (MEPDG) is to provide the highway community with a state-of-the-practice method for the design and analysis of new and rehabilitated pavement structures, based on mechanistic-empirical (ME) principles. This means that the design/analysis procedure calculates pavement responses (stresses, strains, and deflections) and uses those responses to compute incremental damage over time. The procedure empirically relates the cumulative damage to observed pavement distresses. The flowchart in Figure 1-1 illustrates this ME-based procedure. The AASHTOWare Pavement ME Design® is the commercially available software tool. The AASHTOWare software is referred to in this manual as PMED.

The AASHTOWare PMED represents a major change in the way pavement design is performed. AASHTOWare PMED predicts multiple performance indicators (refer to Figure 1-1) and it provides a direct tie between materials, structural design, construction, climate, traffic, and pavement management systems. Figures 1-2 and 1-3 are examples of the interrelationship between these activities for asphalt concrete (AC) and Portland cement concrete (PCC) materials.

1.1 Purpose of Manual

This manual of practice presents information to guide pavement design engineers in making decisions and using AASHTOWare PMED for new pavement and rehabilitation design. The manual does not provide guidance on developing regional or local calibration factors for predicting pavement distress and smoothness. A separate document, *Guide for the Local Calibration of the Mechanistic-Empirical Pavement Design Guide*, provides guidance for determining the local calibration factors for both AC and PCC pavement types (2).

1.2 Overview of the Design Procedure

AASHTOWare PMED is a production-ready design tool to support the day-to-day operations of public and private pavement engineers. When analyzing a pavement design project using

AASHTOWare PMED, whether it is new construction, an overlay, or restoration, utilize the following three-step, basic process:

1. Create a trial design for the project.
2. Run AASHTOWare PMED to predict the key distresses and smoothness for the trial design.
3. Review the predicted performance of the trial design against performance criteria, then modify the trial design as needed in order to produce a feasible design that satisfies the performance criteria at the selected reliability level.

Pavement responses (stresses, strains, and deflections) are combined with other pavement, traffic, climate, and materials parameters to predict the progression of key pavement distresses and smoothness loss over time. These outputs are the basis for checking the adequacy of a trial design. AASHTOWare PMED software also includes an automated process or feature to iterate to an optimized pavement thickness for both flexible and rigid pavements.

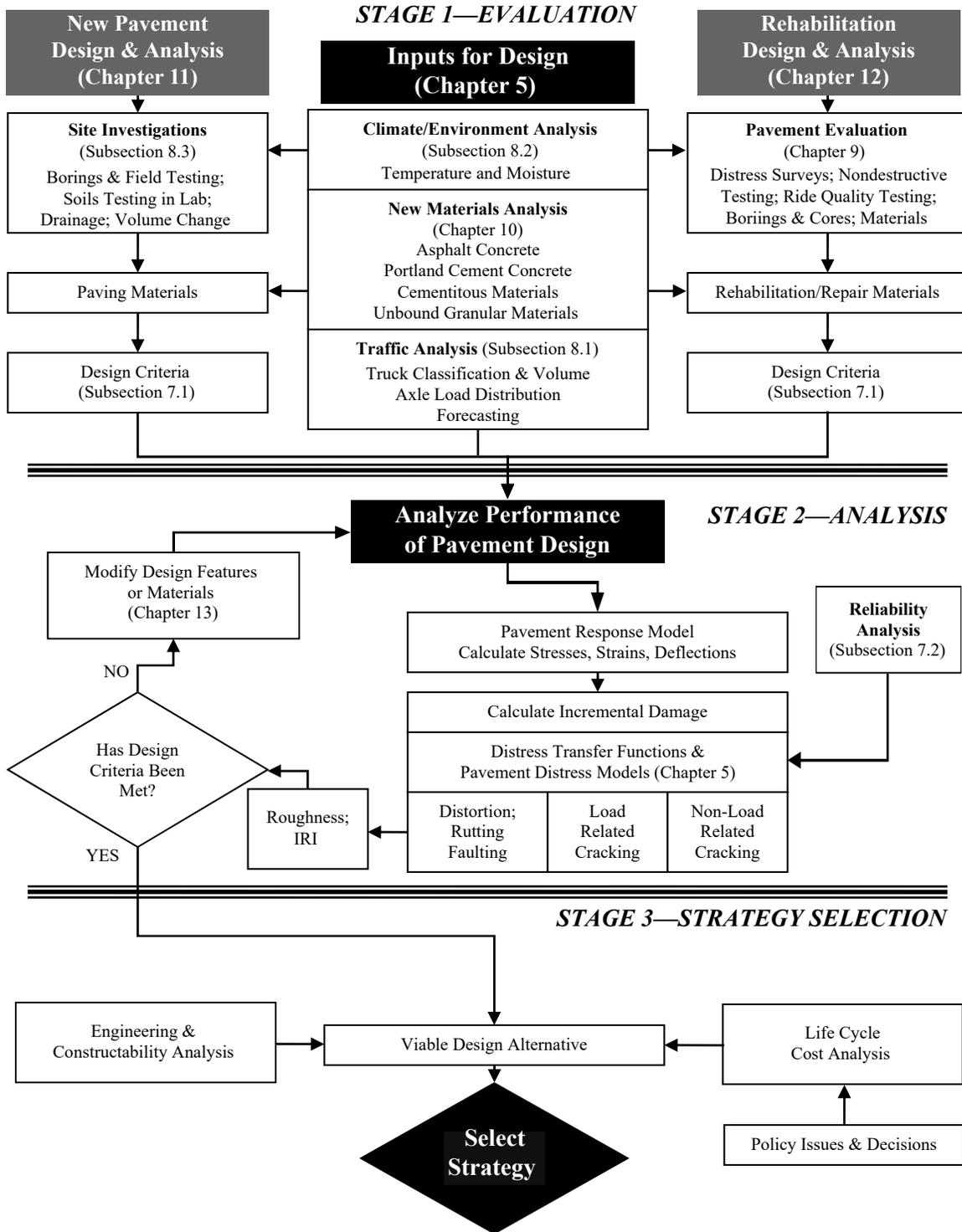


Figure 1-1. Conceptual Flow Chart of the Three-Stage Design/Analysis Process for AASHTOWare PMED

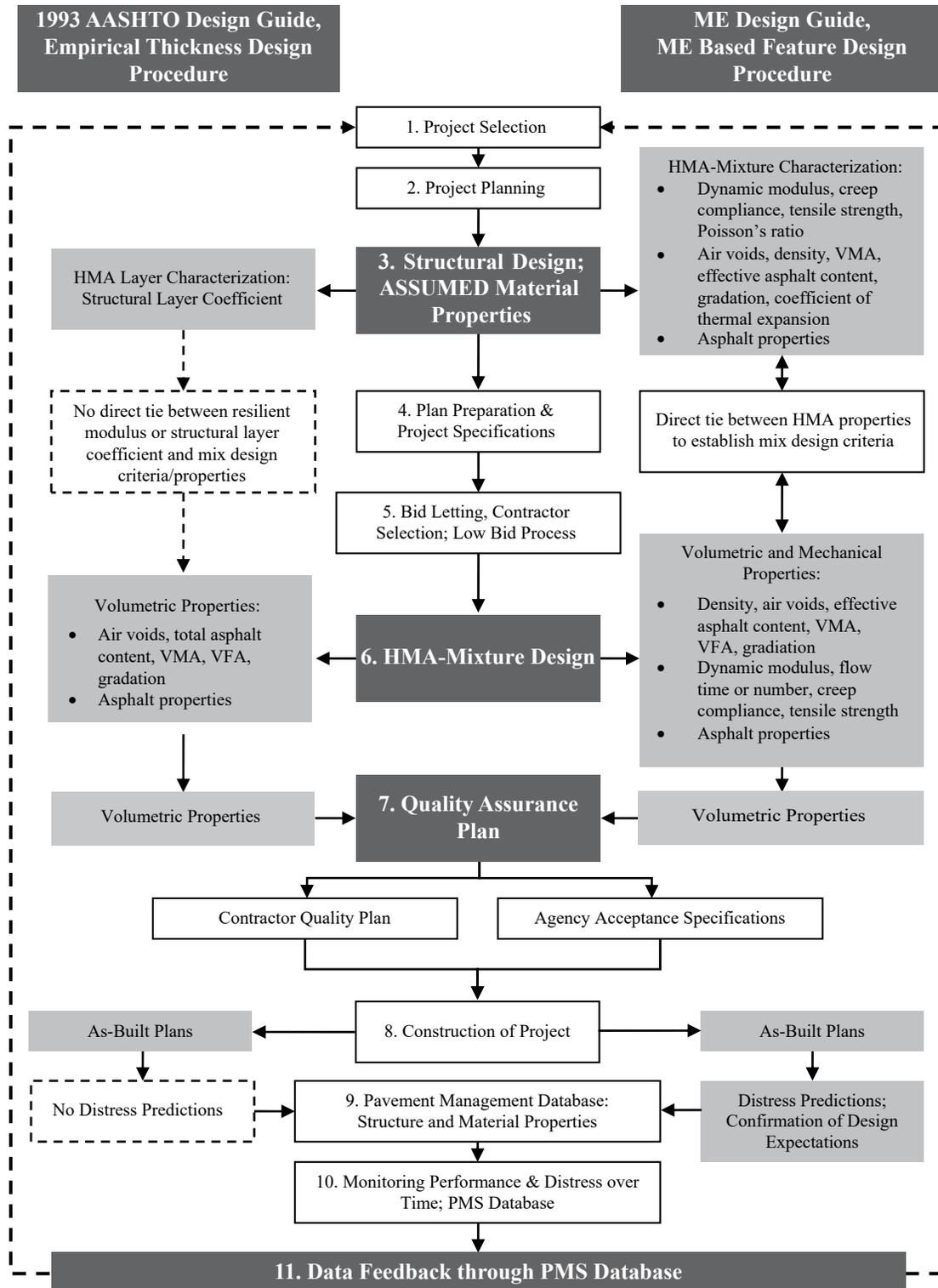


Figure 1-2. Typical Differences between Empirical Design Procedures and an Integrated ME Design System, in Terms of AC Mixture Characterization

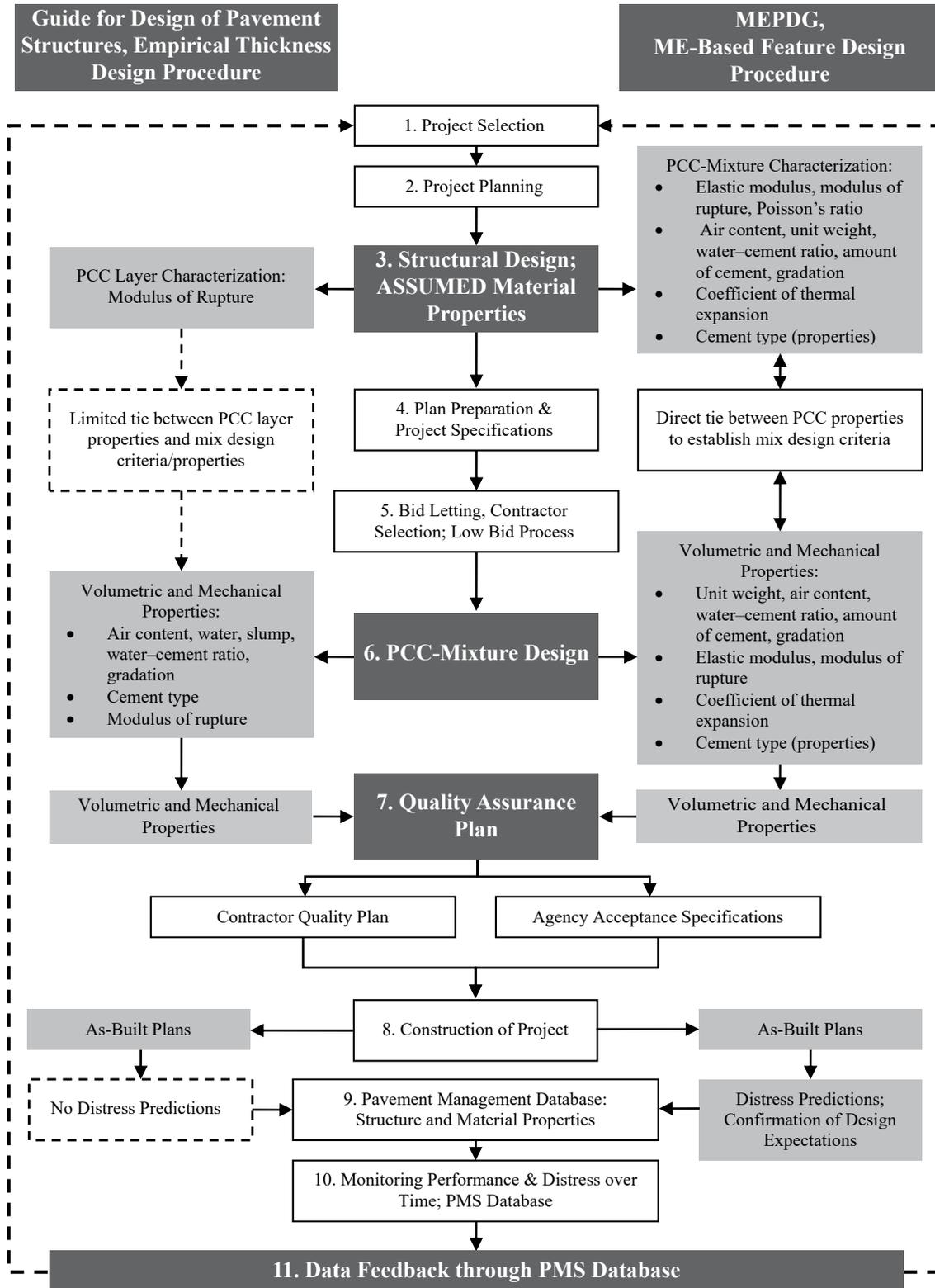


Figure 1-3. Typical Differences between Empirical Design Procedures and an Integrated ME Design System, in Terms of PCC-Mixture Characterization

The ME approach makes it possible to optimize the design and to fully verify that specific distress types will be limited to values less than the failure criteria within the design life of the pavement structure. The basic steps included in the MEPDG are listed below and presented as flow charts in Figures 1-4 and 1-5. The steps shown in Figures 1-4 and 1-5 are referenced to the appropriate sections within this manual of practice.

1. **Select a trial design strategy.** The pavement designer may use an agency-specific procedure to determine the trial design cross section.
2. **Select the appropriate performance indicator criteria (threshold value) and design reliability level for the project.** Design or performance indicator criteria include magnitudes of key pavement distresses and smoothness that may trigger major rehabilitation or reconstruction. These criteria could be a part of an agency’s policies for deciding when to rehabilitate or reconstruct. AASHTOWare PMED allows the user to select the performance indicator criteria to be considered. The user can uncheck the box next to the criteria that do not need to be considered. (See Chapter 4.1 for definitions.)
3. **Obtain all inputs for the pavement trial design under consideration.** This step may be a time-consuming effort, but it is what separates the MEPDG from other design procedures. The MEPDG allows the designer to determine inputs using a hierarchical structure in which the effort to quantify a given input is selected based on the importance of the project, importance of the input, and available resources. The required inputs to run the software are obtained using one of three levels of effort that need not be consistent for all of the inputs for a given design. This permits the user to use the “best available” data for all inputs. The hierarchical input levels are defined in Chapters 4 and 5, and are grouped under six broad topics: (1) general project information, (2) design criteria, (3) traffic, (4) climate, (5) structure layering, and (6) material properties (including the design features). *A caution to the designer—Some of the input parameters are interrelated; changing one parameter may affect the value of another input parameter. The designer should use caution in making changes in individual parameters.*
4. **Run AASHTOWare PMED and examine the inputs and outputs for engineering reasonableness.** The software calculates changes in layer properties, damage, key distresses, and the International Roughness Index (IRI) over the design life. The substeps for step 4 include:
 - a. Examine the input summary to verify the inputs are correct. This step should be completed after each run, until the designer becomes more familiar with the program and its inputs.
 - b. Examine the outputs that comprise the intermediate process—specific parameters (such as climate values), monthly load transfer efficiency (LTE) values for rigid pavement analysis, monthly layer modulus values for flexible and rigid pavement analysis to determine their reasonableness, and calculated performance indicators (pavement distresses and IRI). This step may be completed after each run or

until the designer becomes more familiar with the program. Review of important intermediate processes and steps is presented in Chapter 13.

- c. Assess whether the trial design has met each of the performance indicator criteria at the design reliability level chosen for the project. As noted above, IRI is an output parameter predicted over time and a measure of surface smoothness. IRI is calculated from other distress predictions (refer to Figure 1-1), site factors, and initial IRI.
- d. If any of the criteria are not met, determine how this deficiency can be remedied by altering the materials used, the layering of materials, layer thickness, or other design features.

5. **Revise the trial design, as needed.** If the trial design has input errors, material output anomalies, or has exceeded the failure criteria at the given level of reliability, revise the inputs/trial design and rerun the program. An automated process to iterate to an optimized thickness is done by AASHTOWare PMED to produce a feasible design.

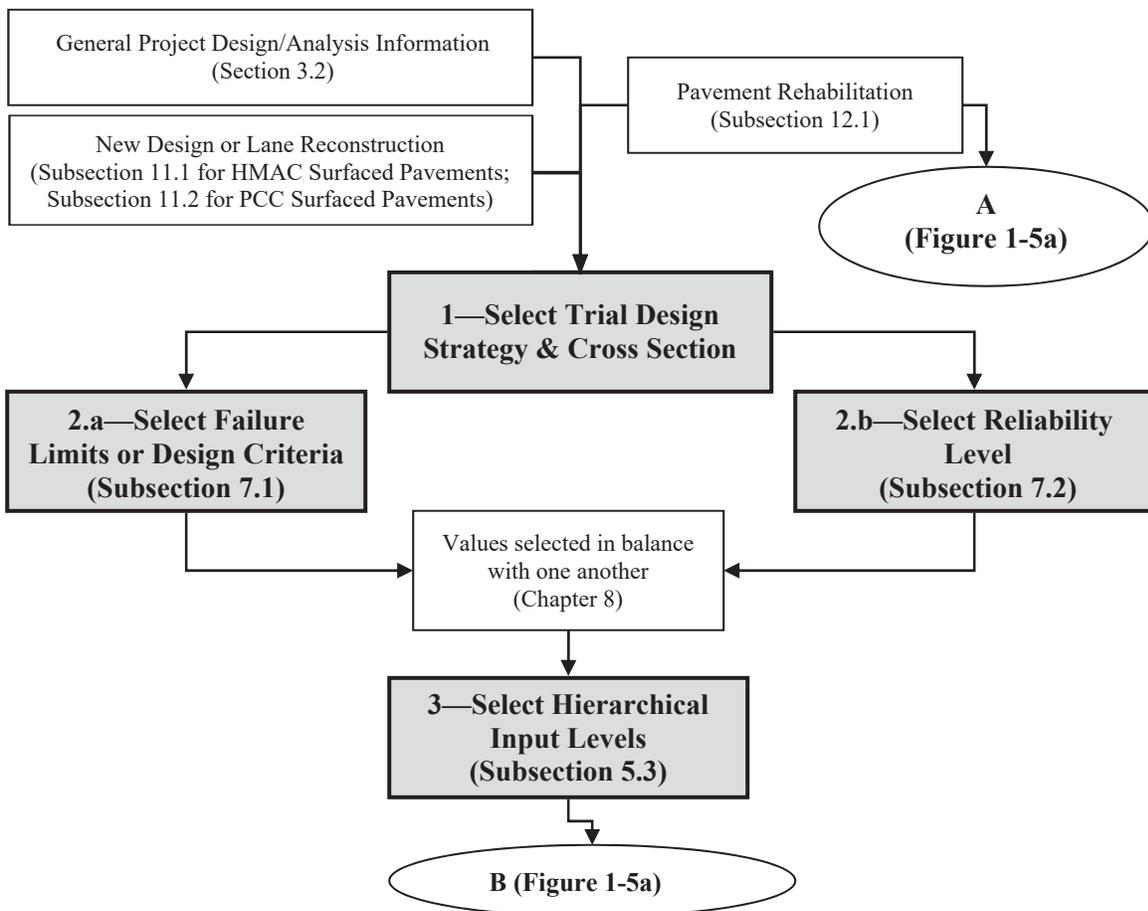


Figure 1-4. Flow Chart of the Steps That Are More Policy Decision Related and Needed to Complete an Analysis of a Trial Design Strategy

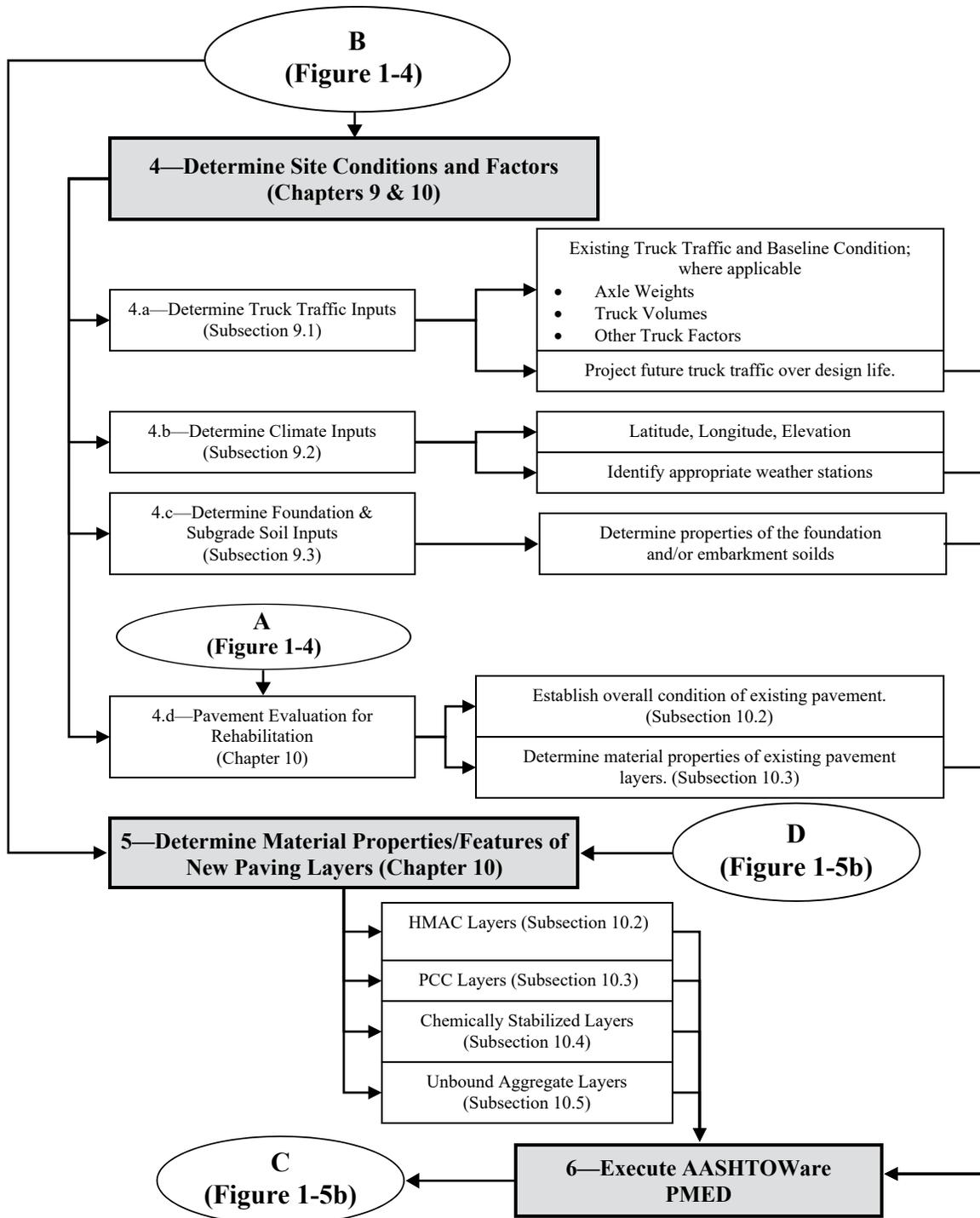


Figure 1-5a. Flow Chart of the Steps Needed to Complete an Analysis of a Trial Design Strategy

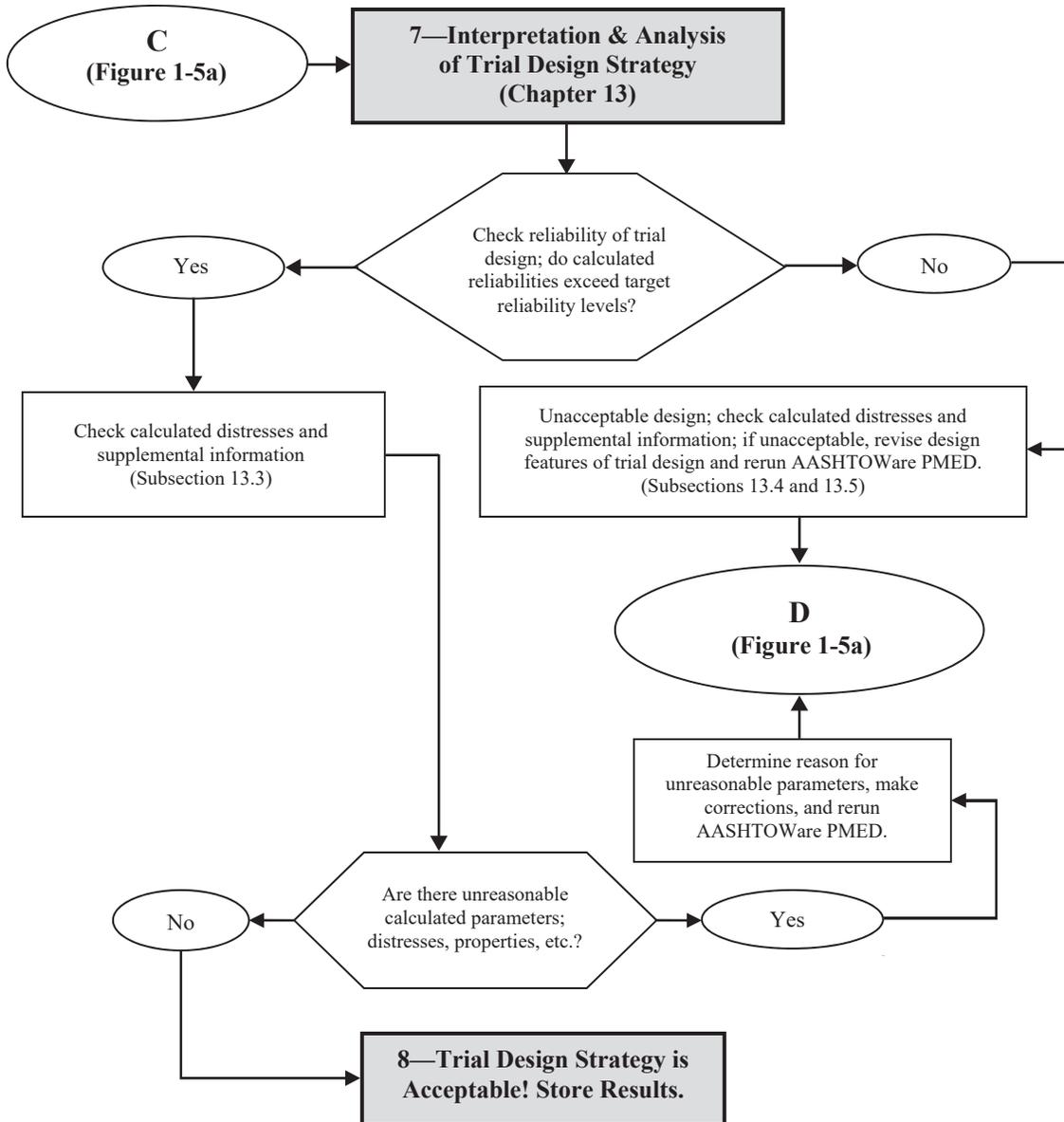


Figure 1-5b. Flow Chart of the Steps Needed to Complete an Analysis of a Trial Design Strategy